

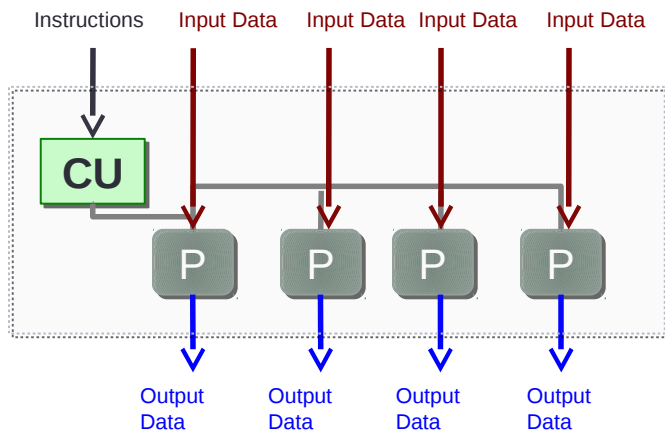
DISTRIBUTED MEMORY PROGRAMMING WITH MPI

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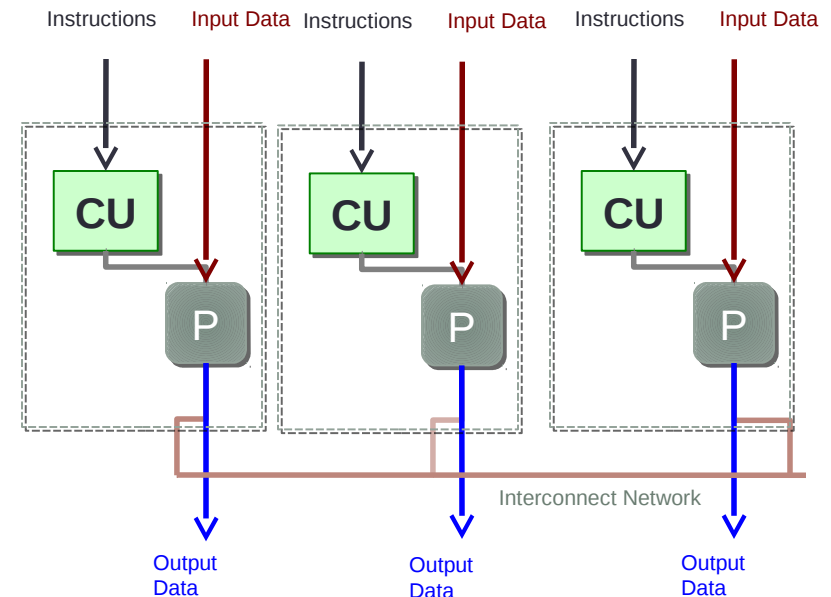


Remember Special Features of Architecture

- Remember “concurrency”: it exploits better the resources (shared) within a computer.
- Exploit SIMD and MIMD Architectures

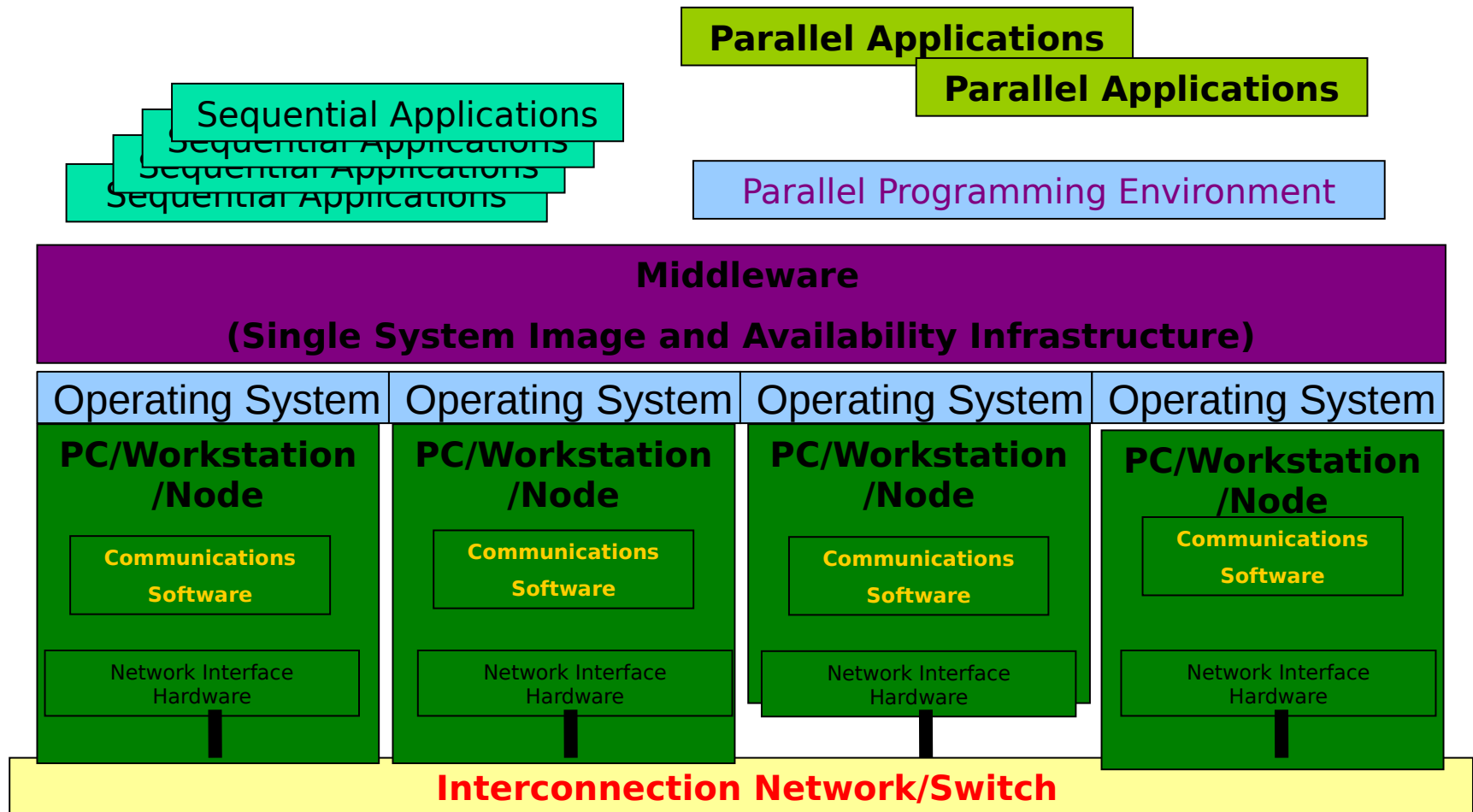


SIMD



MIMD

Cluster Computing Architecture



Distributed Computing Paradigms

- Communication Models:
 - Message Passing
 - Shared Memory
- Computation Models:
 - Functional Parallel
 - Data Parallel

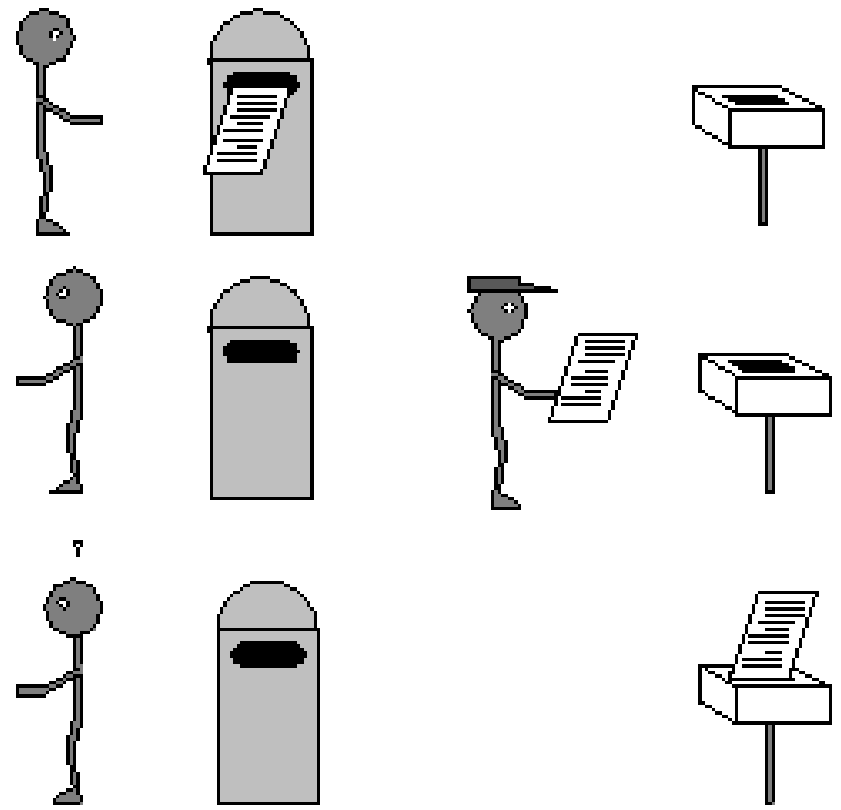
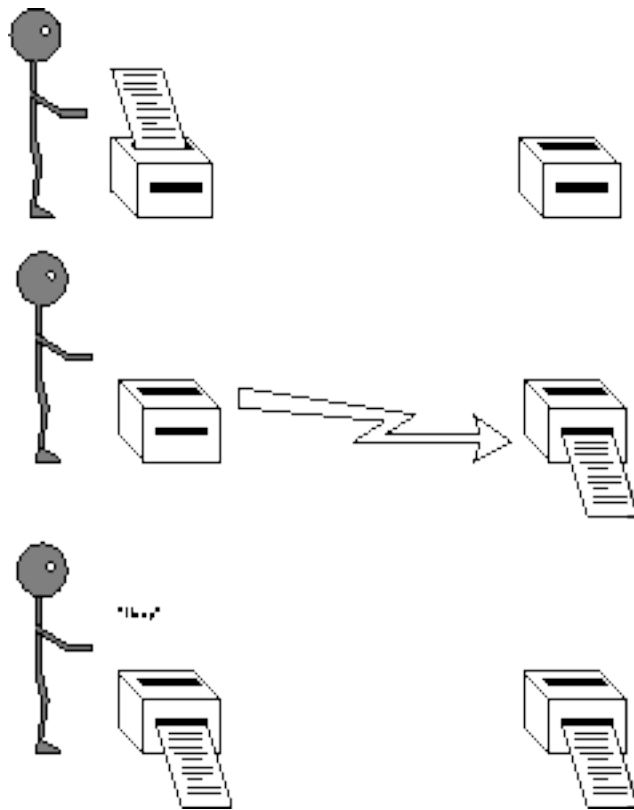
Message Passing

- A process is a program counter and address space.
- Message passing is used for communication among processes.
- Inter-process communication:
 - Type:
Synchronous / Asynchronous
 - Movement of data from one process's address space to another's

Synchronous Vs. Asynchronous

- A synchronous communication is not complete until the **message** has been received.
- An asynchronous communication completes as soon as the **message** is on the way.

Synchronous Vs. Asynchronous (cont.)



What is message passing?

- Data transfer.
- Requires cooperation of sender and receiver
- Cooperation not always apparent in code

- **MPI in a nutshell**

- It is a library specification
- Works natively with C and Fortran
- Not a specific implementation or product
- Scalable
 - Must handle multiple machines
- Portable
 - Sockets API change from one OS to another
 - Handles Big-endian/little-endian architectures
- Efficient
 - Optimized communication algorithms
 - Allow communication and computation overlap

MPI - Message Passing Interface



MPI - Message Passing Interface

- **MPI References**

- Books

- Using MPI: Portable Parallel Programming with the Message Passing Interface, by Gropp, Lusk, and Skejellum, MIT Press, 1994.
 - MPI: The Complete Reference, by Snir, Otto, Huss-Lederman, Walker, and Dongarra, MIT Press, 1996.
 - Parallel Programming with MPI, by Peter Pacheco, Morgan Kaufmann, 1997.

- The standard:

- at <http://www.mpi-forum.org>

MPI History

- 1990 PVM: Parallel Virtual Machine (Oak Ridge Nat'l Lab)
 - Message-passing routines
 - Execution environment (spawn + control parallel processes)
 - No an industry standard
- 1992 meetings (Workshop, Supercomputing'92)
- 1993 MPI draft
- 1994 MPI Forum (debates)
- 1994 MPI-1.0 release (C & Fortran bindings) + standardization
- 1995 MPI-1.1 release
- 1997 MPI-1.2 release (errata) + MPI-2 release (new features, C++ & Fortran 90 bindings)
- ????? MPI-3 release (new: FT, hybrid, p2p, RMA, ...)
- 2000 MPI (ch), Madeline, V4....
- 2005 OpenMPI...

MPI Programming

- **MPI**
 - Use of a single program, on multiple data
 - What does it do?
 - way of identifying process
 - Independent of low-level API
 - Optimized communication
 - Allow communication and computation overlap
 - What does it do not?
 - gain performance of application for free
 - application must be adapted

Features of MPI

- General
 - Communications combine context and group for message security.
 - Thread safety can't be assumed for MPI programs.

Features that are NOT part of MPI

- Process Management
- Remote memory transfer
- Threads
- Virtual shared memory

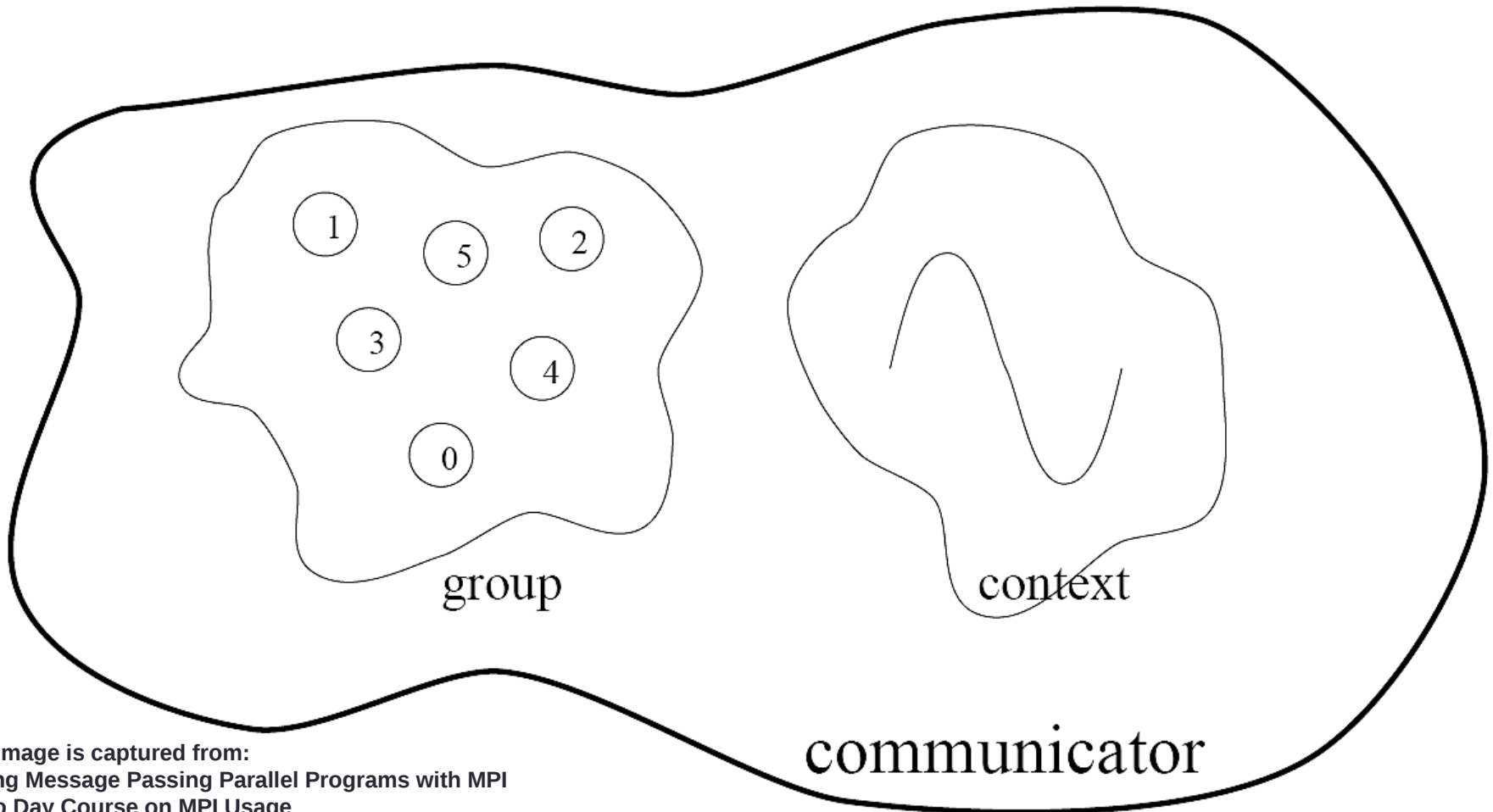
Why to use MPI?

- MPI provides a powerful, efficient, and portable way to express parallel programs.
- MPI was explicitly designed to enable libraries which may eliminate the need for many users to learn (much of) MPI.
- Portable !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
- Good way to learn about subtle issues in parallel computing

How big is the MPI library?

- Huge (125 Functions).
- Basic (6 Functions).

Group and Context



Group and Context (cont.)

- Are two important and indivisible concepts of MPI.
- Group: is the set of processes that communicate with one another.
- Context: it is somehow similar to the frequency in radio communications.
- Communicator: is the central object for communication in MPI. Each communicator is associated with a group and a context.

Communication Modes

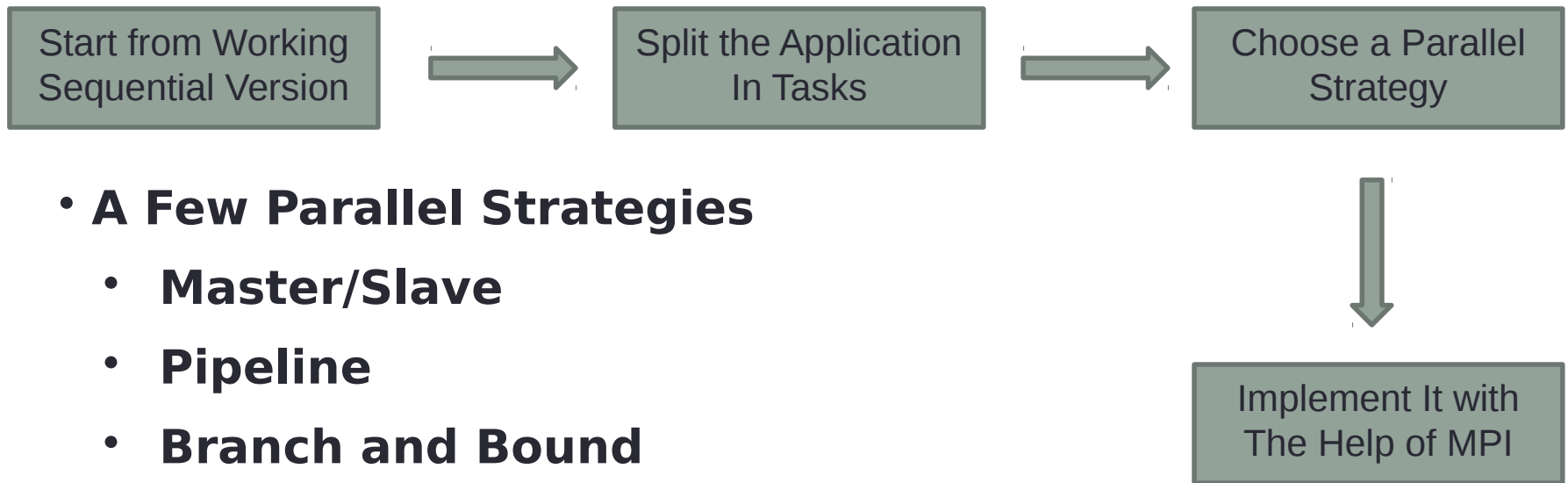
- Based on the type of send:
 - Synchronous: Completes once the acknowledgement is received by the sender.
 - Buffered send: completes immediately, unless if an error occurs.
 - Standard send: completes once the message has been sent, which may or may not imply that the message has arrived at its destination.
 - Ready send: completes immediately, if the receiver is ready for the message it will get it, otherwise the message is dropped silently.

Blocking vs. Non-Blocking

- Blocking, means the program will not continue until the communication is completed.
- Non-Blocking, means the program will continue, without waiting for the communication to be completed.

MPI Programming

- **Possible Programming Workflow**



Parallel Strategies

- **Master/Slave**
 - **Master is one process that centralizes all tasks**
 - **Slaves starve for work**



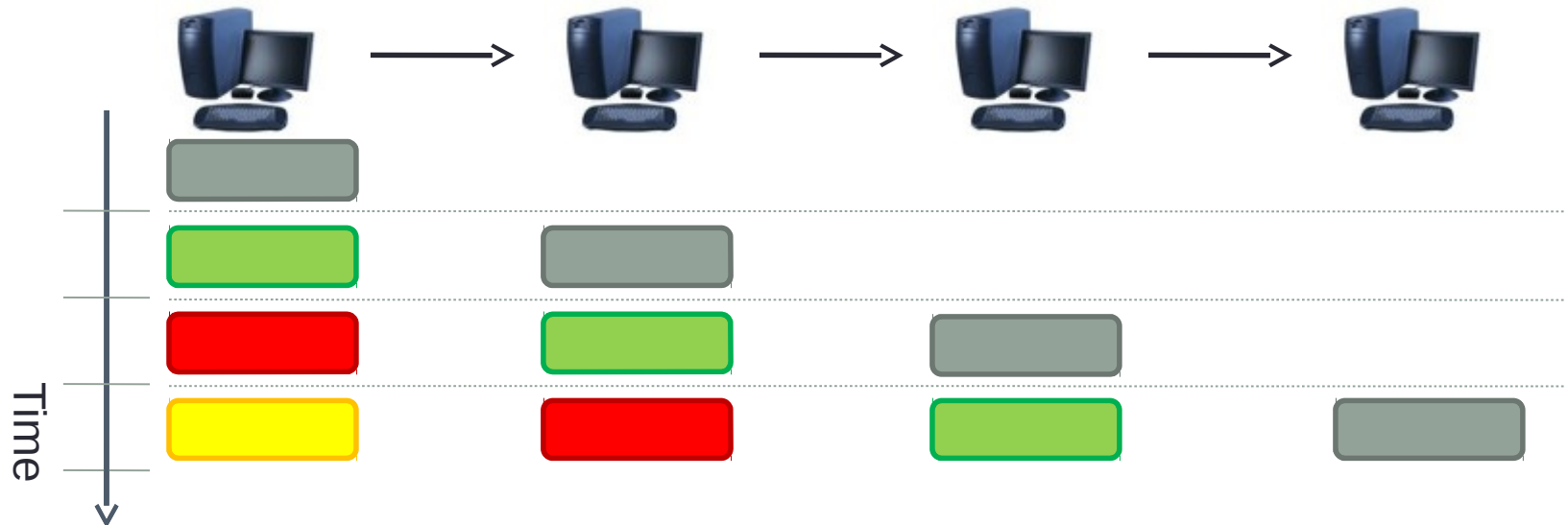
Parallel Strategies

- **Master/Slave**
 - **Master is often the bottleneck**
 - **Scalability is limited due to centralization**
 - **Possible to use replication to improve performance**
 - **It is adaptable to heterogeneous platforms**

Parallel Strategies

- **Pipeline**
 - Each process plays a specific role, pipeline stages
 - Data follows in a single direction
 - Parallelism is achieved when the pipeline is full

- Task 1
- Task 2
- Task 3
- Task 4

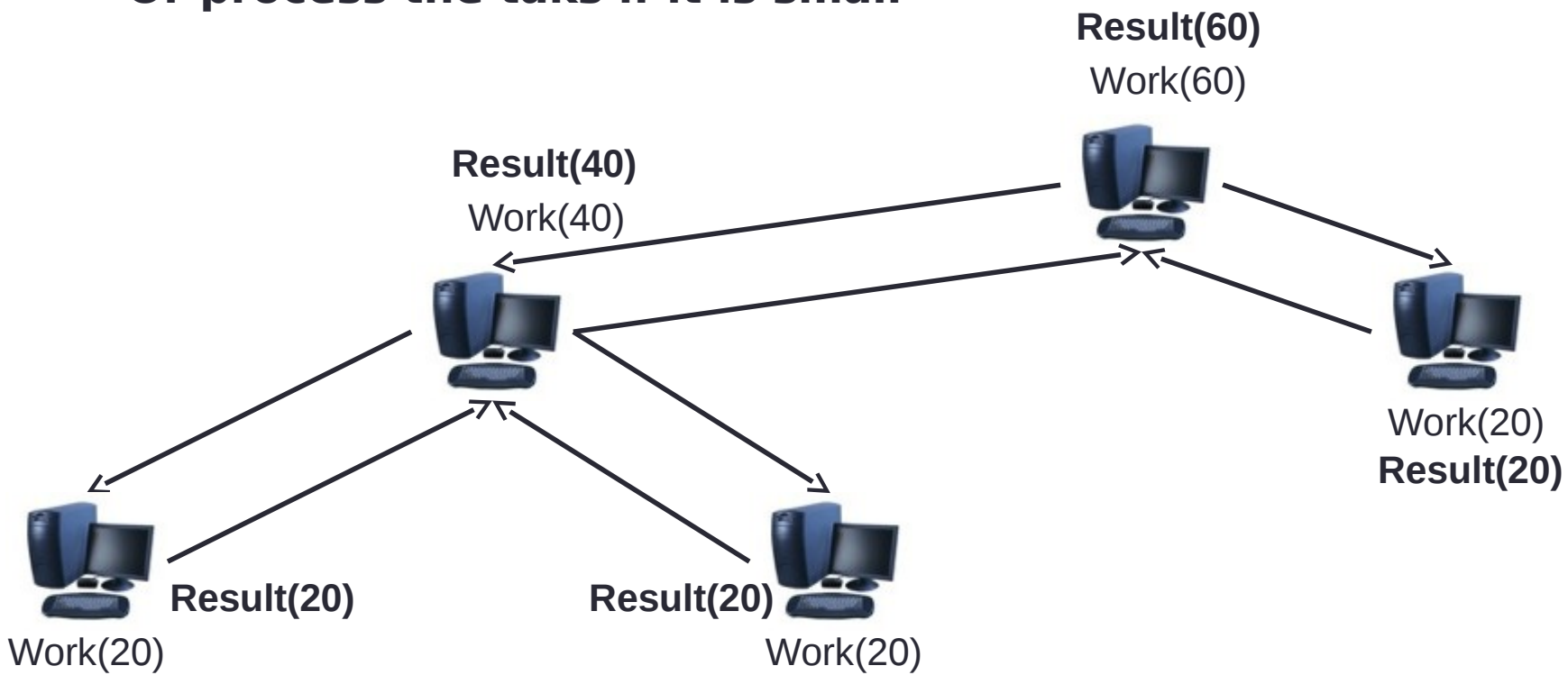


Parallel Strategies

- **Pipeline**
 - **Scalability is limited by the number of stages**
 - **Synchronization may lead to bubbles**
 - **Slow sender**
 - **Fast receiver**
 - **Difficult to use on heterogenous platforms**

Parallel Strategies

- **Divide and Conquer**
 - **Recursevely partion task on roughly equal sized tasks**
 - **Or process the taks if it is small**



Parallel Strategies

- **Divide and Conquer**
 - **More scalable**
 - **Possible to use replicated branches**
 - **In practice is difficult to split tasks**
 - **Suitable for branch and bound algorithms**

MPI Programming

- **Installing**

- Some common MPI implementations, all free:
 - OpenMPI
<http://www.open-mpi.org/>
 - MPICH-2
<http://www.mcs.anl.gov/research/projects/mpich2/>
 - LAM/MPI
<http://www.lam-mpi.org/>

MPI Programming

- **Installing**

- I'm using MPICH-2
- Installed in Ubuntu 10.04 Lucid Lynx with
 - \$ sudo apt-get install mpich2**
- Should work for most Debian based distributions
- Must create a local configuration file
 - \$ echo "MPD_SECRET_WORD=ChangeMe" > ~/.mpd.conf**

MPI Programming

- Test program

```
#include <mpi.h>
#include <stdio.h>

int main(int argc, char **argv){

    /* Initialize MPI */
    MPI_Init(&argc, &argv);

    printf("Test Program\n");

    /* Finalize MPI */
    return MPI_Finalize();
}
```

Skeleton MPI Program

```
#include <mpi.h>

main( int argc, char** argv )
{
    MPI_Init( &argc, &argv );

    /* main part of the program */

    /*
     Use MPI function call depend on your data
     partitioning and the parallelization
     architecture
     */

    MPI_Finalize();
}
```

A minimal MPI program(c)

```
#include "mpi.h"
#include <stdio.h>
int main(int argc, char *argv[])
{
    MPI_Init(&argc, &argv);
    printf("Hello, world!\n");
    MPI_Finalize();
    Return 0;
}
```


MPI Programming

- **Compiling**

- Compiled with gcc, but a mpicc script is provided to invoke gcc with specific MPI options enabled

```
$ mpicc mpi_program.c -o my_mpi_executable
```

- Executed with a special script

```
$ mpirun -np 1 my_mpi_executable
```

```
$ mpirun -np 2 my_mpi_executable
```

```
$ mpirun -np 3 my_mpi_executable
```

MPI Programming

- **Running**

- Compiled with gcc, but a mpicc script is provided to invoke gcc with specific mpi functions

```
$ mpicc mpi_program.c -o my_mpi_executable
```

- For a complete list of parameters try

```
$ man mpicc
```

- Executed with a special script

```
$ mpirun -np 2 my_mpi_executable
```

A minimal MPI program(c) (cont.)

- #include “mpi.h” provides basic MPI definitions and types.
- MPI_Init starts MPI
- MPI_Finalize exits MPI
- Note that all non-MPI routines are local; thus “printf” run on each process
- Note: MPI functions return error codes or MPI_SUCCESS

Error handling

- By default, an error causes all processes to abort.
- The user can have his/her own error handling routines.
- Some custom error handlers are available for downloading from the net.

Improved Hello (c)

```
>include <mpi.h#
#include <stdio.h>
int main(int argc, char *argv[])
{
    int rank, size;
    MPI_Init(&argc, &argv);
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);
    MPI_Comm_size(MPI_COMM_WORLD, &size);
    printf("I am %d of %d\n", rank, size);
    MPI_Finalize();
    return 0;
}
```

MPI Programming

- **How many processing units are available?**

```
int MPI_Comm_size(MPI_Comm comm, int *pcomm_size)
```

- Group of process to communicate
- Default Communicator: For grouping all process use **MPI_COMM_WORLD**
- **pcomm_size**
 - Passed as reference will return the total amount of process in this communicator

Data Types

- The data message which is sent or received is described by a triple (address, count, datatype).
- The following data types are supported by MPI:
 - Predefined data types that are corresponding to data types from the programming language.
 - Arrays.
 - Sub blocks of a matrix
 - User defined data structure.
 - A set of predefined data types

Basic MPI types

MPI datatype

C datatype

MPI_CHAR	signed char
MPI_SIGNED_CHAR	signed char
MPI_UNSIGNED_CHAR	unsigned char
MPI_SHORT	signed short
MPI_UNSIGNED_SHORT	unsigned short
MPI_INT	signed int
MPI_UNSIGNED	unsigned int
MPI_LONG	signed long
MPI_UNSIGNED_LONG	unsigned long
MPI_FLOAT	float
MPI_DOUBLE	double
MPI_LONG_DOUBLE	long double

MPI Programming

- **Exercise 1 - Hello World**
 - **Create program that prints hello world and the total number of available process on the screen**
 - **Use -np with a variable number to verify that your program is working**

MPI Programming

- **Exercise 2 - Who am I**
 - **If I am process 0**
 - **Prints: “hello world”**
 - **else**
 - **Prints: “I’m process <ID>”**
 - **Replacing <ID> by the process rank**

Why defining the data types during the send of a message?

Because communications take place between heterogeneous machines. Which may have different data representation and length in the memory.

MPI blocking send

```
MPI_SEND(void *start, int  
count, MPI_DATATYPE datatype, int dest,  
int tag, MPI_COMM comm)
```

- The message buffer is described by (**start**, **count**, **datatype**).
- **dest** is the rank of the target process in the defined communicator.
- **tag** is the message identification number.

MPI blocking receive

```
MPI_RECV(void *start, int count,  
MPI_DATATYPE datatype, int source, int tag,  
MPI_COMM comm, MPI_STATUS *status)
```

- **Source** is the rank of the sender in the communicator.
- The receiver can specify a wildcard value for source (MPI_ANY_SOURCE) and/or a wildcard value for tag (MPI_ANY_TAG), indicating that any source and/or tag are acceptable
- **Status** is used for extra information about the received message if a wildcard receive mode is used.
- If the count of the message received is less than or equal to that described by the MPI receive command, then the message is successfully received. Else it is considered as a buffer overflow error.

MPI_STATUS

- Status is a data structure
- In C:

```
int recvd_tag, recvd_from, recvd_count;
MPI_Status status;
MPI_Recv(..., MPI_ANY_SOURCE, MPI_ANY_TAG, ...,
         &status)
recvd_tag = status.MPI_TAG;
recvd_from = status.MPI_SOURCE;
MPI_Get_count(&status, datatype, &recvd_count);
```

More info

- A receive operation may accept messages from an arbitrary sender, but a send operation must specify a unique receiver.
- Source equals destination is allowed, that is, a process can send a message to itself.

Why MPI is simple?

- Many parallel programs can be written using just these six functions, only two of which are non-trivial;
 - MPI_INIT
 - MPI_FINALIZE
 - MPI_COMM_SIZE
 - MPI_COMM_RANK
 - MPI_SEND
 - MPI_RECV

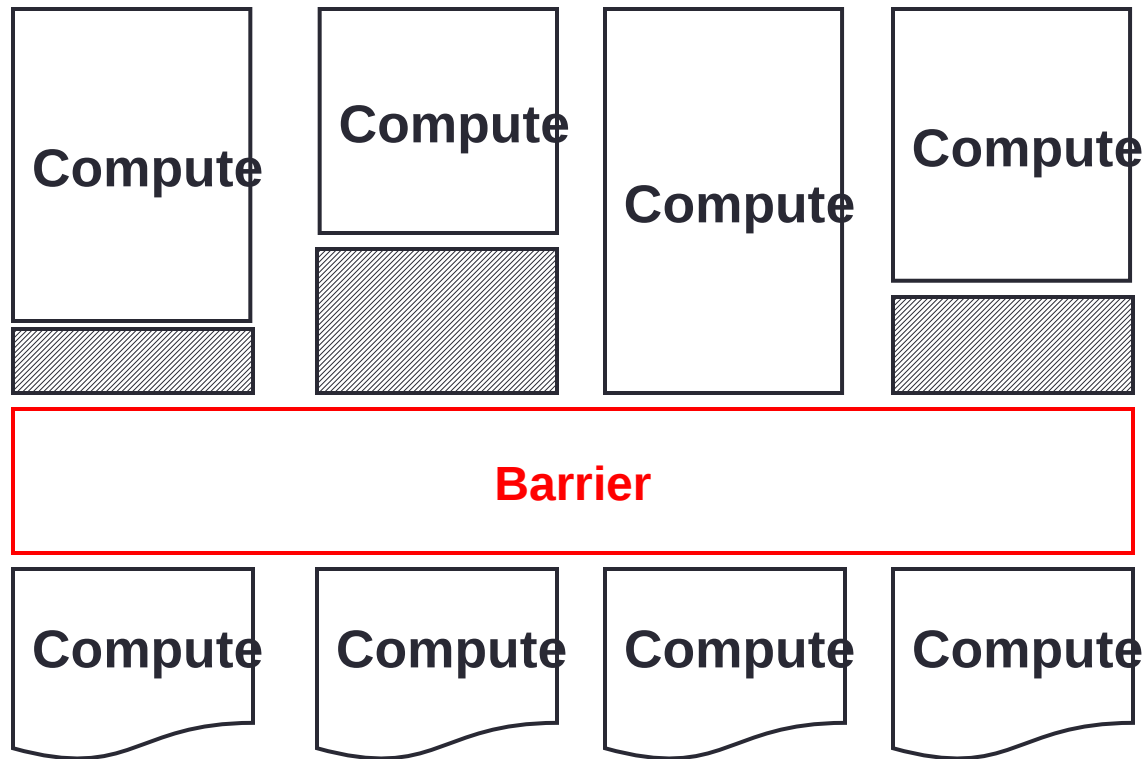
Collective Communications

- Point-to-point communications involve pairs of processes.
- Many message passing systems provide operations which allow larger numbers of processes to participate

Types of Collective Transfers

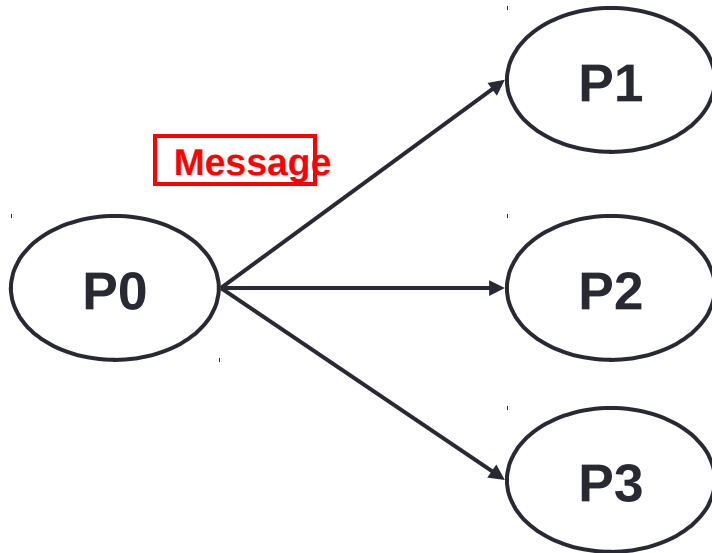
- Barrier
 - Synchronizes processors
 - No data is exchanged but the barrier blocks until all processes have called the barrier routine
- Broadcast (sometimes multicast)
 - A broadcast is a one-to-many communication
 - One processor sends one message to several destinations
- Reduction
 - Often useful in a many-to-one communication

Barrier

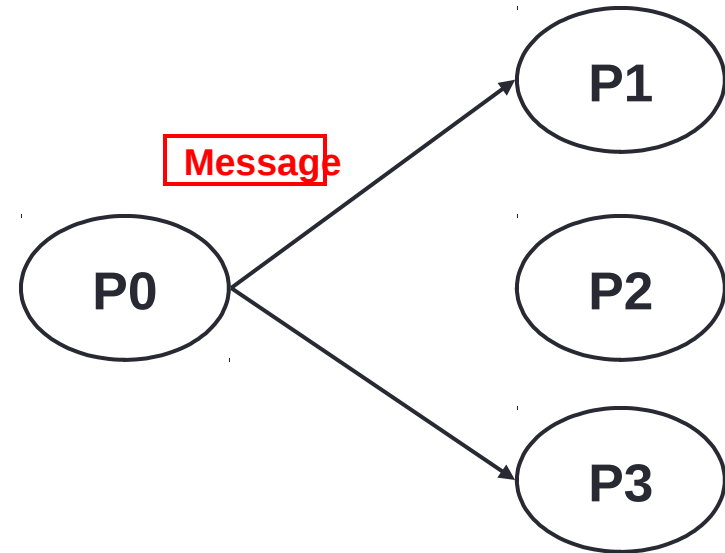


Broadcast and Multicast

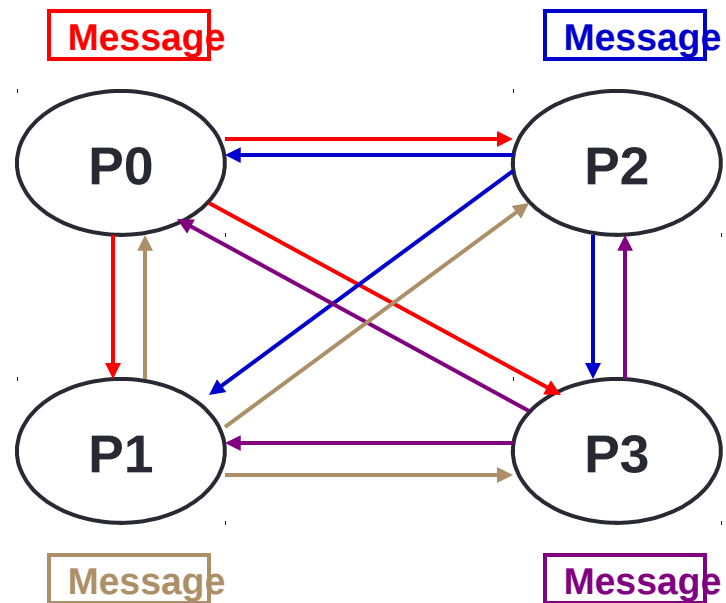
Broadcast



Multicast

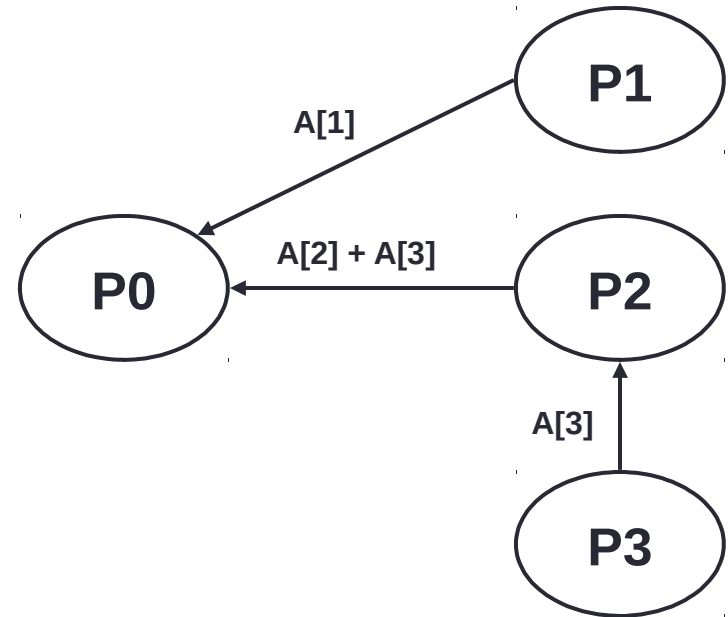
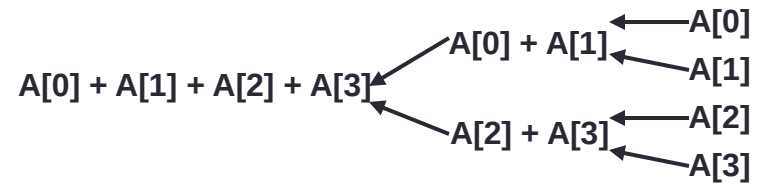
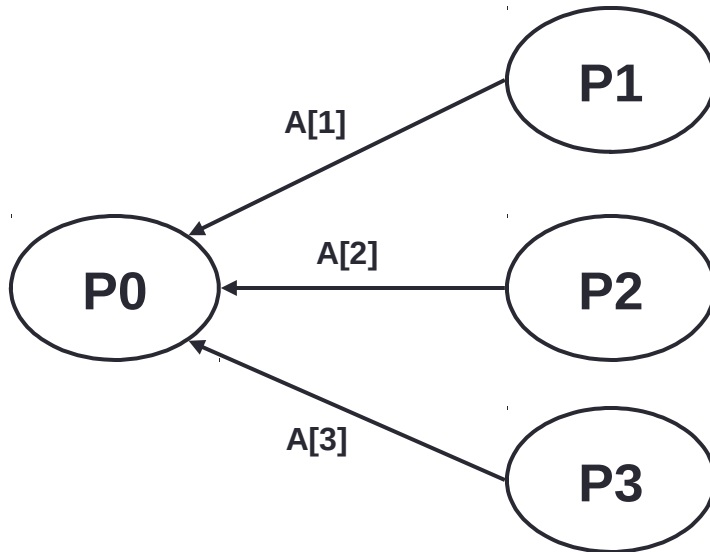


All-to-All



Reduction

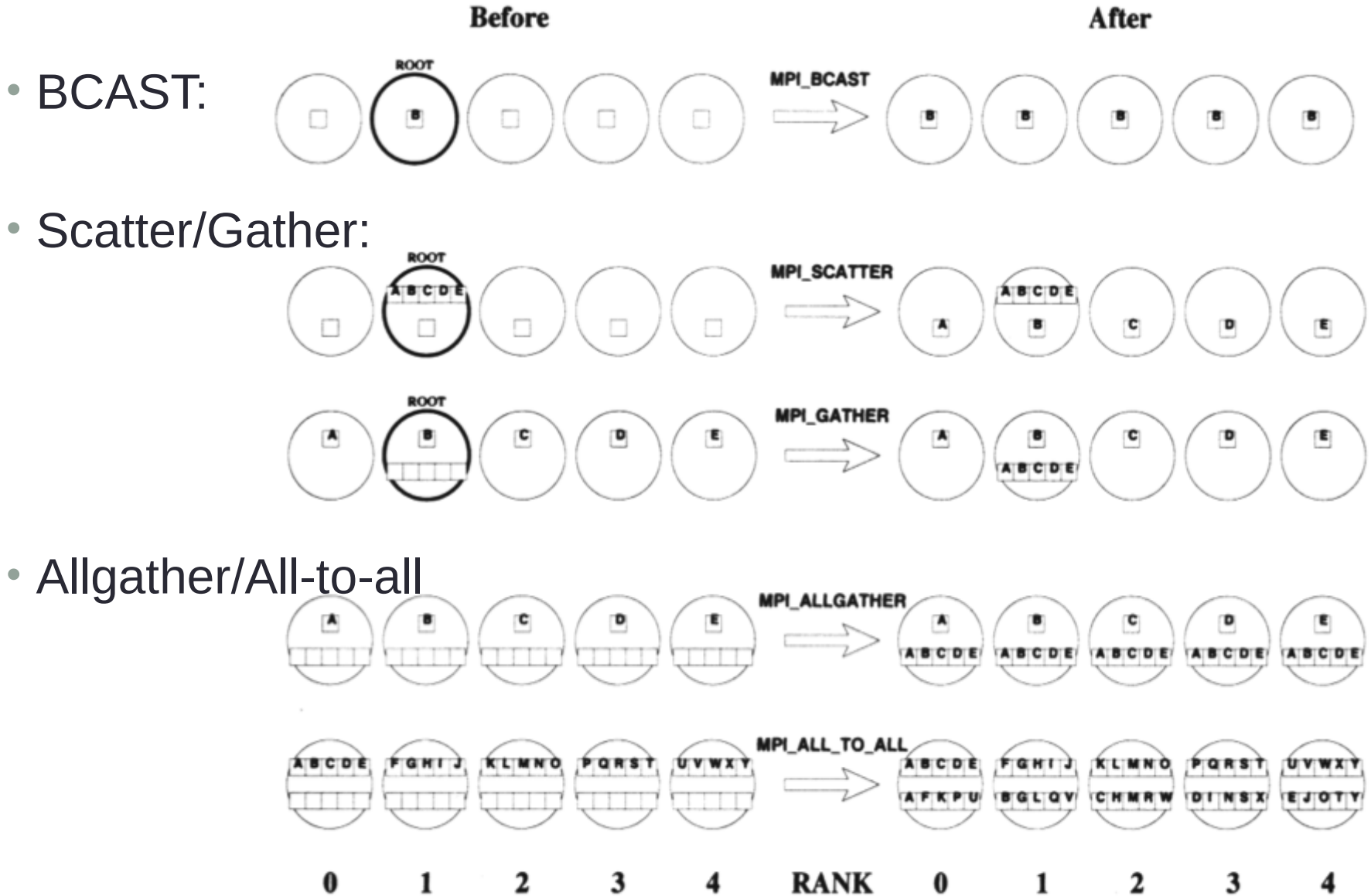
```
sum ← 0
for i ← 1 to p do
  sum ← sum + A[i]
```



Introduction to Collective Operations in MPI

- Collective ops are called by **all** processes in a communicator.
 - No tags
 - Blocking
- **MPI_BCAST** distributes data from one process (the root) to **all others** in a communicator.
- **MPI_REDUCE/ALLREDUCE** combines data from all processes in communicator and returns it to one process.
- In many numerical algorithms, **SEND/RECEIVE** can be replaced by **BCAST/REDUCE**, improving both simplicity and efficiency.
- Others:
 - **MPI_[ALL]SCATTER[V]/[ALL]GATHER[V]**

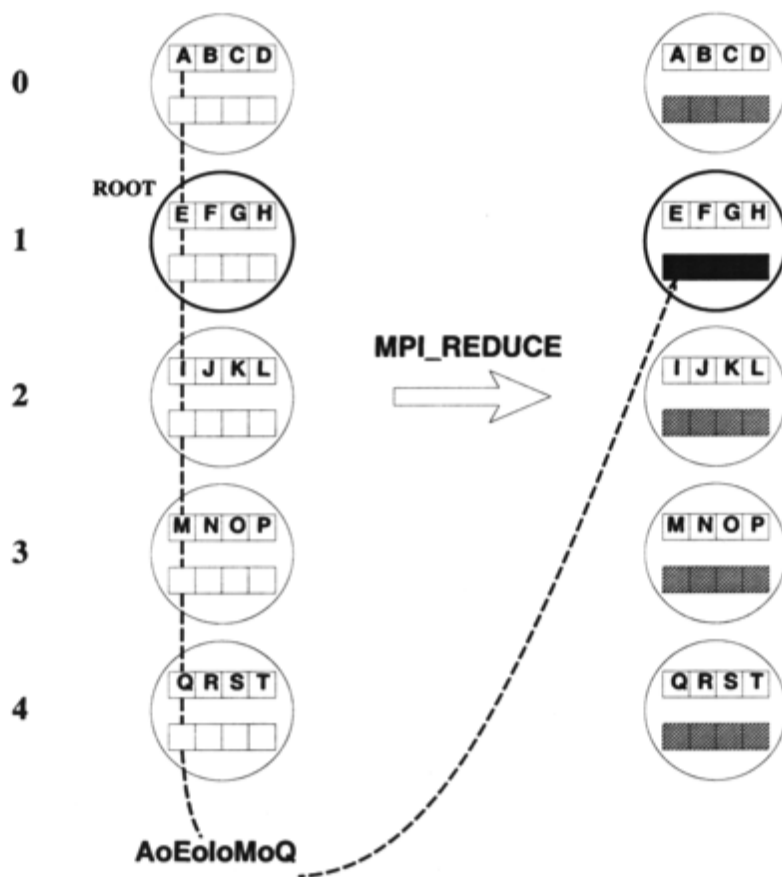
Collectives at Work



Collectives at Work (2)

- Reduce:

RANK

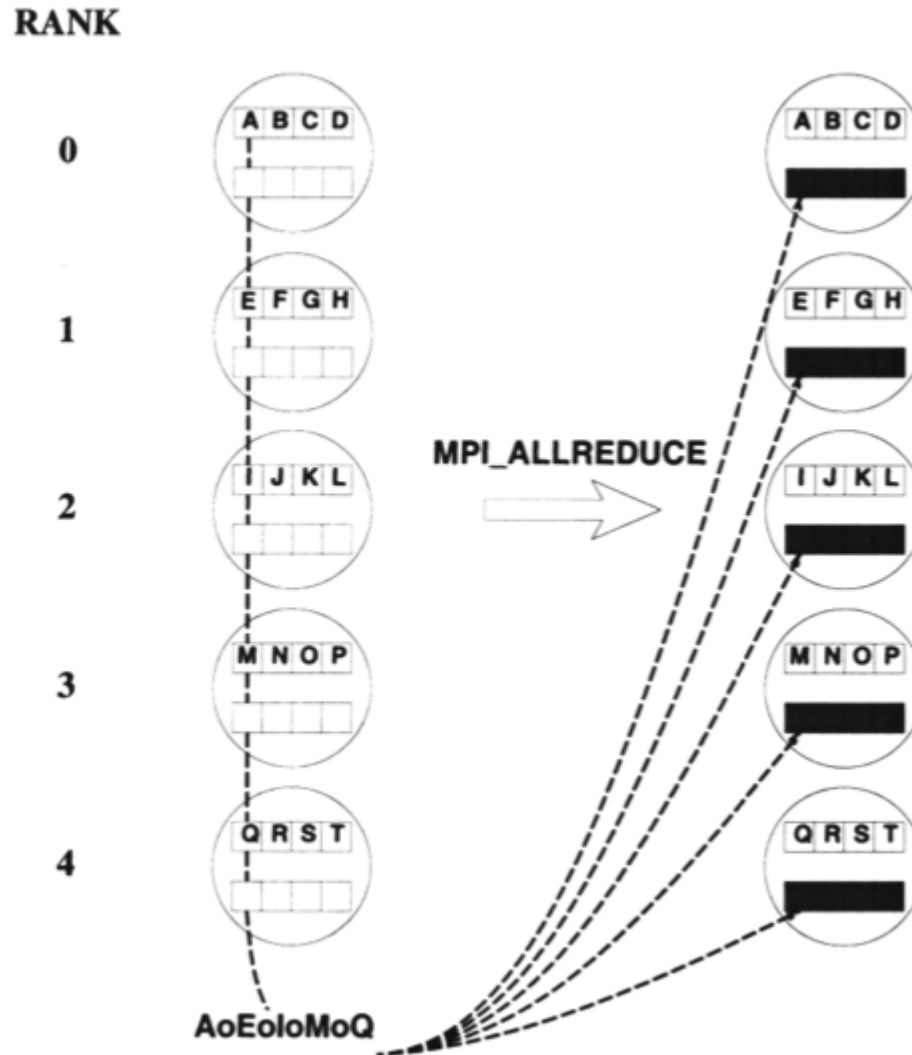


- Predefined Ops (associative & commutative) / user ops (assoc.)

MPI Name	Function
MPI_MAX	Maximum
MPI_MIN	Minimum
MPI_SUM	Sum
MPI_PROD	Product
MPI_LAND	Logical AND
MPI_BAND	Bitwise AND
MPI_LOR	Logical OR
MPI_BOR	Bitwise OR
MPI_LXOR	Logical exclusive OR
MPI_BXOR	Bitwise exclusive OR
MPI_MAXLOC	Maximum & location
MPI_MINLOC	Minimum & location

Collectives at Work (3)

- Allreduce:



Simple full example

```
#include <stdio.h>
#include <mpi.h>

int main(int argc, char *argv[])
{
    const int tag = 42;          /* Message tag */
    int id, ntasks, source_id, dest_id, err, i;
    MPI_Status status;
    int msg[2]; /* Message array */

    err = MPI_Init(&argc, &argv); /* Initialize MPI */
    if (err != MPI_SUCCESS) {
        printf("MPI initialization failed!\n");
        exit(1);
    }
    err = MPI_Comm_size(MPI_COMM_WORLD, &ntasks); /* Get nr of tasks */
    err = MPI_Comm_rank(MPI_COMM_WORLD, &id); /* Get id of this process */
    if (ntasks < 2) {
        printf("You have to use at least 2 processors to run this program\n");
        MPI_Finalize(); /* Quit if there is only one processor */
        exit(0);
    }
}
```

Simple full example (Cont.)

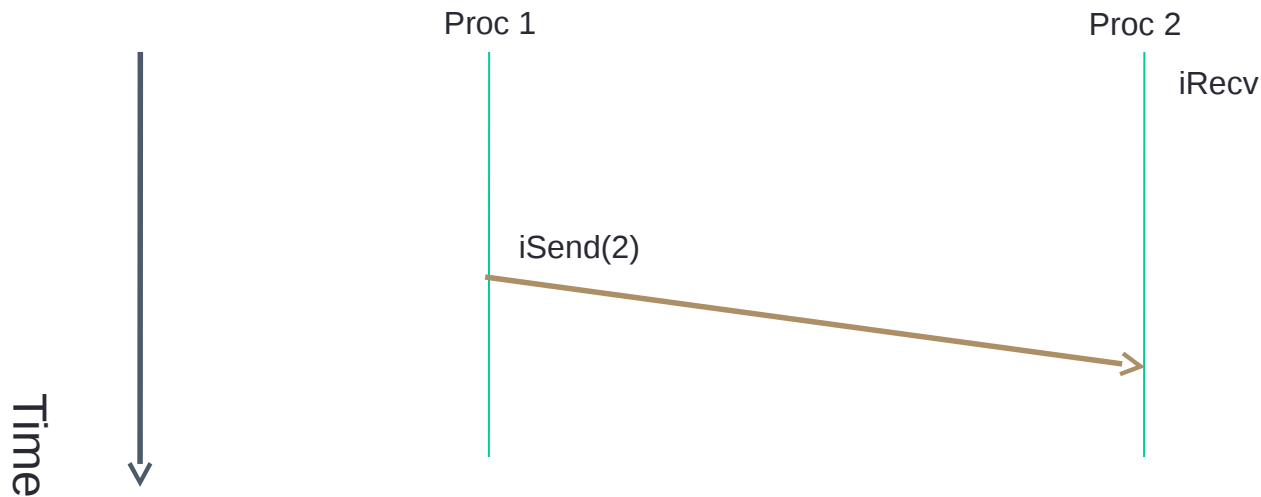
```
if (id == 0) { /* Process 0 (the receiver) does this */
    for (i=1; i<ntasks; i++) {
        err = MPI_Recv(msg, 2, MPI_INT, MPI_ANY_SOURCE, tag, MPI_COMM_WORLD, \
                        &status); /* Receive a message */
        source_id = status.MPI_SOURCE; /* Get id of sender */
        printf("Received message %d %d from process %d\n", msg[0], msg[1], \
               source_id);
    }
}
else { /* Processes 1 to N-1 (the senders) do this */
    msg[0] = id; /* Put own identifier in the message */
    msg[1] = ntasks; /* and total number of processes */
    dest_id = 0; /* Destination address */
    err = MPI_Send(msg, 2, MPI_INT, dest_id, tag, MPI_COMM_WORLD);
}

err = MPI_Finalize(); /* Terminate MPI */
if (id==0) printf("Ready\n");
exit(0);
return 0;
}
```

MPI
One-to-one
Communication

- **Asynchronous/Non-Blocking**

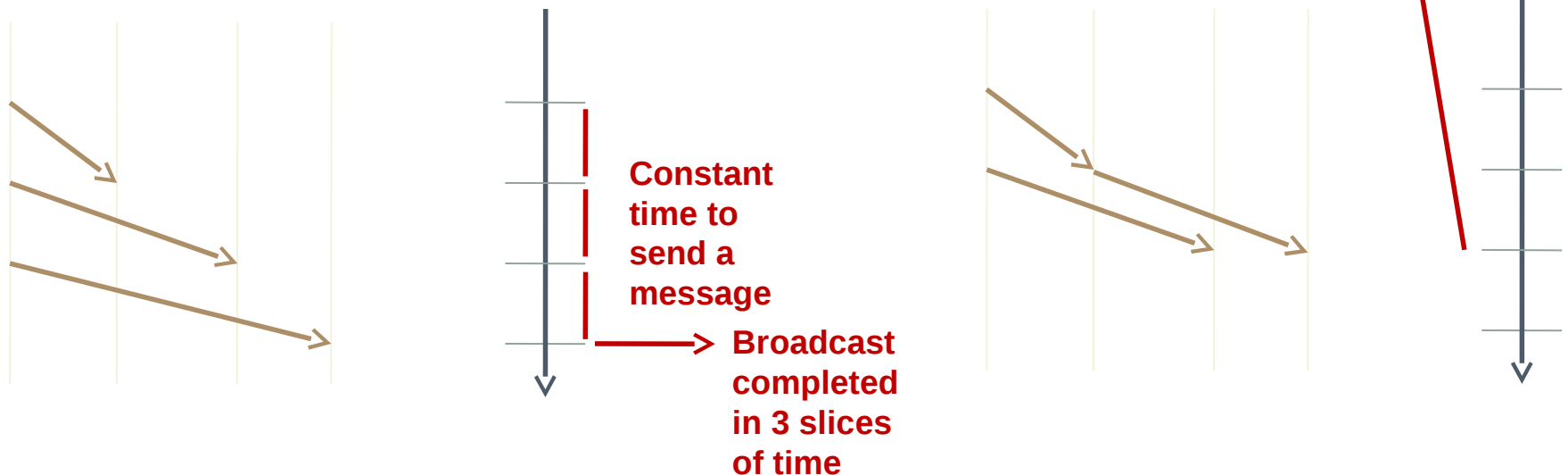
- Process signs it is waiting for a message
- Continue working meanwhile



MPI Collective Communication

- **Process master wants to send a message to everybody**

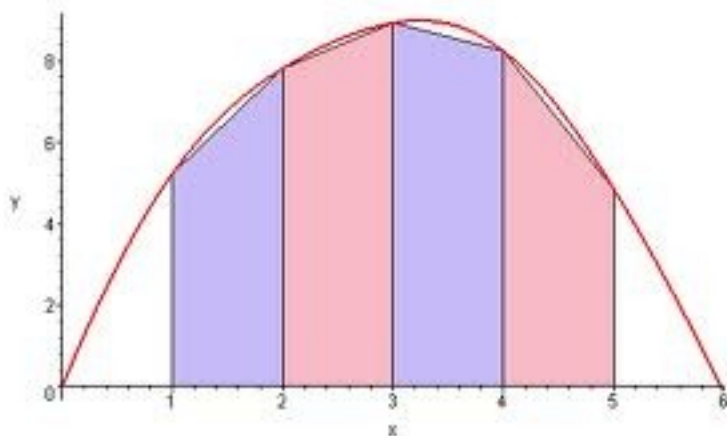
- First solution, process master send $N-1$ messages
- Optimized collective communication send in parallel



Work@class

-

$$\pi = \int_0^1 \frac{4}{(1+x^2)} dx$$



Example: Compute PI (1)

```
#include "mpi.h"
#include <math.h>

int main(int argc, char *argv[])
{
    int done = 0, n, myid, numprocs, I, rc;
    double PI25DT = 3.141592653589793238462643;
    double mypi, pi, h, sum, x, a;
    MPI_INIT(&argc, &argv);
    MPI_COMM_SIZE(MPI_COMM_WORLD, &numprocs);
    MPI_COMM_RANK(MPI_COMM_WORLD, &myid);
    while (!done)
    {
        if (myid == 0)
        {
            printf("Enter the number of intervals: (0 quits) ");
            scanf("%d", &n);
        }
        MPI_BCAST(&n, 1, MPI_INT, 0, MPI_COMM_WORLD);
        if (n == 0)
        }
    }
}
```


Example: Compute PI (2)

```
h = 1.0 / (double)n;
sum = 0.0;
for (i = myid + 1; i <= n; i += numprocs)
{
    x = h * ((double)i - 0.5);
    sum += 4.0 / (1.0 + x * x);
}
mypi = h * sum;
MPI_Reduce(&mypi, &pi, 1, MPI_DOUBLE, MPI_SUM, 0,
MPI_COMM_WORLD);

if (myid == 0) printf("pi is approximately %.16f, Error is
%.16f\n", pi, fabs(pi - PI25DT));

MPI_Finalize();
return 0;
}
```

Profiling Support: PMPI

- Profiling layer of MPI
- Implemented via additional API in MPI library
 - Different name: `PMPI_Init()`
 - Same functionality as `MPI_Init()`
- Allows user to:
 - define own `MPI_Init()`
 - Need to call `PMPI_Init()`:
- User may choose subset of MPI routines to be profiled
- Useful for building performance analysis tools
 - Vampir: Timeline of MPI traffic (Etnus, Inc.)
 - Paradyn: Performance analysis (U. Wisconsin)
 - mpiP: J. Vetter (LLNL)
 - ScalaTrace: F. Mueller et al. (NCSU)

```
MPI_Init(...) {  
    collect pre stats;  
    PMPI_Init(...);  
    collect post stats;  
}
```

When to use MPI

- Portability and Performance
- Irregular data structure
- Building tools for others
- Need to manage memory on a per processor basis

Summary

- The parallel computing community has cooperated on the development of a standard for message-passing libraries.
- There are many implementations, on nearly all platforms.
- MPI subsets are easy to learn and use.
- Lots of MPI material is available.

Para Observar y Ejecutar

- http://people.sc.fsu.edu/~jburkardt/cpp_src/mpi/mpi.html

<https://computing.llnl.gov/tutorials/mpi/>